

# **GR5xx HRS RSCS Relay Example Application**

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# Preface

#### Purpose

This document introduces how to use and verify a Heart Rate Sensor & Running Speed and Cadence Sensor Relay (HRS RSCS Relay) example in the Bluetooth Low Energy (Bluetooth LE) GR5xx Software Development Kit (SDK), to help users quickly get started with secondary development.

### Audience

This document is intended for:

- Device user
- Developer
- Test engineer
- Hobbyist developer
- Technical writer

#### **Release Notes**

This document is the third release of *GR5xx HRS RSCS Relay Example Application*, corresponding to Bluetooth LE GR5xx System-on-Chip (SoC) series.

#### **Revision History**

Version	Date	Description
1.0	2023-01-10	Initial release
3.0	2023-03-30	Updated descriptions about GR5xx SoCs.
3.1	2023-11-06	Updated the approaches for obtaining GProgrammer and GRToolbox.

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## **1** Introduction

The Heart Rate Sensor & Running Speed and Cadence Sensor Relay (HRS RSCS Relay) example demonstrates how to apply GR5xx System-on-Chips (SoCs) in scenarios with multi-roles (Peripheral and Central) and multi-connections, to enable functions of an HRS RSCS Relay device. The HRS RSCS Relay device can serve as both a collector and a sensor.

Collector

As a GATT Client, the HRS RSCS Relay device receives measurement data from heart rate sensor as well as running speed and cadence sensor.

Sensor

As a GATT Server, the HRS RSCS Relay device sends the received data to other collectors, such as GRToolbox, a Bluetooth Low Energy (Bluetooth LE) debugging App for GR5xx SoCs.

This document introduces how to use and verify an HRS RSCS Relay example in the GR5xx Software Development Kit (SDK).

Before getting started, you can refer to the following documents.

Name	Description			
GR5xx Sample Service Application	Introduces how to apply and customize Goodix Sample Service in developing Bluetooth LE			
and Customization	applications based on GR5xx SDK.			
Developer guide of the specific GR5xx	Introduces GR5vy SDK and how to develop and debug applications based on the SDK			
SoC	introduces GR5xx SDK and now to develop and debug applications based on the SDK.			
Bluetooth Core Spec	Offers official Bluetooth standards and core specification from Bluetooth SIG.			
Bluataath GATT Spac	Provides details about Bluetooth profiles and services. Available at https://www.bluetooth.com/			
Bidetootil GALL Spec	specifications/gatt.			
LLink/LTrace User Guide	Provides J-Link operational instructions. Available at <u>https://www.segger.com/downloads/jlink/</u>			
J-Linky J-Mace User Guide	UM08001_JLink.pdf.			
Koil Usor Guido	Offers detailed Keil operational instructions. Available at https://www.keil.com/support/man/			
	docs/uv4/.			

#### Table 1-1 Reference documents

## 2 Profile Overview

The HRS RSCS Relay example implements the following profiles:

- Standard profiles: Heart Rate Profile as well as Running Speed and Cadence Profile, which are defined by Bluetooth SIG
- Custom profile: Goodix HRS RSCS Relay Control Point Profile, which is defined by Goodix

The application scenarios where GRToolbox is used as an HRS RSCS Relay collector are shown in Figure 2-1.



Figure 2-1 Application scenarios

HRS RSCS Relay device registers the following profiles when it is used as a collector:

- Heart Rate Client Profile: Receive measurement data from a heart rate sensor.
- Running Speed and Cadence Client Profile: Receive measurement data from a running speed and cadence sensor.

HRS RSCS Relay device registers the following profiles when it is used as a sensor:

- Heart Rate Server Profile: Relay the received data from a heart rate sensor to GRToolbox.
- Running Speed and Cadence Server Profile: Relay the received data from a running speed and cadence sensor to GRToolbox.
- Goodix HRS RSCS Relay Control Point Profile: Receive control commands from GRToolbox and returns execution outcomes.

Goodix HRS RSCS Relay Control Point Profile includes HRS RSCS Relay Control Point Service (HRRCPS), with a 128-bit vendor-specific UUID of A6ED0601-D344-460A-8075-B9E8EC90D71B.

HRRCPS has the following characteristics:

- HRR Control Point characteristic: Receive control commands from the HRS RSCS Relay collector.
- HRR Control Point Response characteristic: Return execution outcomes to the HRS RSCS Relay collector.

These characteristics are described in detail as follows:

#### Table 2-1 HRRCPS characteristics

Characteristic	UUID	Туре	Support	Security	Property
HRR Control Point	A6ED0602-D344-460A-8075-B9E8EC90D71B	128 bits	Mandatory	None	Write



Characteristic	UUID	Туре	Support	Security	Property
HRR Control Point	46ED0603-D344-4604-8075-R9E8EC90D71B	128 hits	Mandatory	None	Indicate
Response		120 0103	Wandatory	None	malcate

## **3** Initial Operation

This chapter introduces how to quickly verify an HRS RSCS Relay example in the GR5xx SDK.

### **Note**:

SDK\_Folder is the root directory of the GR5xx SDK in use.

## **3.1 Preparation**

Perform the following tasks before running the HRS RSCS Relay example.

• Hardware preparation

Table 3-1 Hardware preparation

Name	Description
Development board	Three Starter Kit Boards (SK Boards) of the corresponding SoC
Connection cable	USB Type C cable (Micro USB 2.0 cable for GR551x SoCs)

#### • Software preparation

#### Table 3-2 Software preparation

Name	Description
Windows	Windows 7/Windows 10
J-Link driver	A J-Link driver. Available at <u>https://www.segger.com/downloads/jlink/</u> .
Keil MDK5	An integrated development environment (IDE). MDK-ARM Version 5.20 or later is required. Available at <u>https://www.keil.com/download/product/</u> .
GRToolbox (Android)	A Bluetooth LE debugging tool. Available at <u>https://www.goodix.com/en/software_tool/</u> grtoolbox.
GProgrammer (Windows)	A programming tool. Available at <u>https://www.goodix.com/en/software_tool/gprogrammer_ble</u> .

## 3.2 Firmware Programming

The source code of the HRS RSCS Relay example is in SDK\_Folder\projects\ble\ble\_multi\_role\ ble\_ app\_hrs\_rscs\_relay.

You can download *ble\_app\_hrs\_rscs\_relay.bin, ble\_app\_hrs.bin,* and *ble\_app\_rscs.bin* to three SK Boards (serving as the Relay device, the HRS device, and the RSCS device respectively) through GProgrammer. For details, see *GProgrammer User Manual.* 

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### 🛄 Note:

- The *ble\_app\_hrs\_rscs\_relay.bin* is in SDK\_Folder\projects\ble\ble\_multi\_role\ble\_app\_hrs\_ rscs\_relay\build.
- The *ble\_app\_hrs.bin* is in SDK\_Folder\projects\ble\ble\_peripheral\ble\_app\_hrs\build.
- The *ble\_app\_rscs.bin* is in SDK\_Folder\projects\ble\ble\_peripheral\ble\_app\_rscs\build.

## 3.3 Test and Verification

When the HRS RSCS Relay device, the HRS device, the RSCS device, and GRToolbox are ready, test and verify the HRS RSCS Relay example. Steps are described as follows:

1. Scan the HRS RSCS Relay device.

Run GRToolbox, and select **Application > RELAY**.

Start scanning and discover a device with the advertising name **Goodix\_HRS\_RSCS\_RELAY** (the advertising name can be modified in *user\_app.c*), as shown in Figure 3-1.



Figure 3-1 Discovering Goodix\_HRS\_RSCS\_RELAY on GRToolbox

#### 🛄 Note:

Screenshots of GRToolbox in this document are for reference only, to help users better understand the software operation. In the case of interface differences due to version changes, the interface of GRToolbox in practice shall prevail.

If the length of the device name exceeds 14 characters, the middle part of the device name is replaced with an ellipsis.



2. Connect to the HRS RSCS Relay device.

Select **Goodix\_HRS\_RSCS\_RELAY** to establish connection, and enter the HRS RSCS RELAY interface.

$\leftarrow$ Relay						
Goodix_HRS_RSCS_RELAY						
<i>≣X</i> ;	((o))	💎				
🔗 Connect RSC		Notify RSC				
🔗 Connect HRS		Notify HRS				
RSC						
Speed	0	km/h				
Distance	0	km				
Total Distance	0	km				
HRS						
Heart Rate	0	BPM				
Sensor Position	N/A	GET				
DI	ISCONNE	ст				

Figure 3-2 HRS RSCS RELAY interface

3. Connect to sensor devices.

Tap  $\mathscr{P}$  to enable the HRS RSCS Relay device to scan and connect to the HRS and RSC devices The interface below is shown after the Relay device is connected to the HRS and RSC devices.

← Relay			
Goodix_HRS_RSC	S_RELAY	,	
<i>=3</i> ;-	(( <sub>1</sub> ))		~
🔗 Disconnect	RSC	Notify RS	sc 🗩
🔗 Disconnect	HRS	Notify HF	as 🕕
RSC			
Speed	0		km/h
Distance	0		km
Total Distance	0		km
HRS			
Heart Rate	0		BPM
Sensor Position	N/A		GET
		_	
(	DISCONN	ECT	)

Figure 3-3 Connecting to the HRS and RSC devices

4. Enable sensor notifications.

Tap > to enable the HRS RSCS Relay device to notify the HRS and RSC devices to report measurement data.

This allows the phone to receive heart rate, running speed, and cadence information relayed from the HRS RSCS Relay device.

← Relay		
Goodix_HRS_RS0	CS_RELAY	
<i>=3</i> ;-	((c))	- 💎
🔗 Disconnec	t RSC N	otify RSC
🔗 Disconnec	t HRS N	otify HRS 🛛 🔵
RSC Speed Distance Total Distance	7.20 7 0.03	km/h m km
HRS Heart Rate	240	ВРМ
Sensor Position	N/A	GET
	DISCONNECT	

Figure 3-4 Enabling HRS and RSC notifications

### 5. Read the HRS device location.

Tap **GET** to enable the HRS RSCS Relay device to read the HRS device location.

← Relay		
Goodix_HRS_RS0	CS_RELAY	
<i>=3</i> ; −	((°))	- 💎
🔗 Disconnec	t RSC N	otify RSC
🔗 Disconnec	t HRS N	otify HRS 🛛 🔵
Speed	7.20	km/h
Distance	37	m
Total Distance	0.25	km
HRS		
Heart Rate	210	BPM
Sensor Position	Finger	GET
	DISCONNECT	-

Figure 3-5 Reading the HRS device location

If GRToolbox displays information as shown above, the HRS RSCS Relay example runs successfully.

# **4** Application Details

This chapter introduces the running procedures and major code of the HRS RSCS Relay example.

## **4.1 Running Procedures**

When the HRS RSCS Relay example starts running, it performs operations such as initializing peripherals and Bluetooth LE Protocol Stack, adding profiles, and enabling advertising. The running procedures of the HRS RSCS Relay example after GRToolbox discovers the advertisement and connection is established are shown in Figure 4-1:



Figure 4-1 Running procedures

### 4.2 Major Code

In the following parts, the HRS device is taken as an example to introduce major code related to interactions between GRToolbox, Relay device, and HRS device.

### 4.2.1 Receiving a Command from GRToolbox

When the HRR Control Point characteristic receives control command data from GRToolbox, it parses the corresponding event and reports to the application layer, and executes the corresponding command.

### Path: user\_app\user\_app.c under the project directory

#### Name: hrrcps\_evt\_process()

```
static void hrrcps_evt_process(hrrcps_evt_t *p_evt)
{
    ...
    switch (p_evt->evt_type)
    {
        case HRRCPS_EVT_CTRL_PT_IND_ENABLE:
            APP_LOG_DEBUG("HRR Control Point Indication is enabled.");
            break;
        case HRRCPS_EVT_CTRL_PT_IND_DISABLE:
            APP_LOG_DEBUG("HRR Control Point Indication is disabled.");
            break;
        ...
        default:
            break;
        ...
    }
    ...
}
```

### 4.2.2 Command to Connect to HRS Device

HRRCPS parses the command and reports the **HRRCPS\_EVT\_SCAN\_HRS** event to the application layer; HRRCPS then starts scanning and searches for the HRS device. After discovering an advertisement, the Relay device judges whether the advertising device is the target device by using app\_adv\_report\_handler() to check whether the advertising data contains HRS UUID. After the target device is discovered, the Relay device stops scanning, then establishes connection with the target device through app\_scan\_stop\_handler(), and finally finds Heart Rate Service through app\_connected\_handler() (these functions are in *user\_app.c*).

Path: user\_app\user\_app.c under the project directory

```
Name: hrrcps_evt_process()
```

```
static void hrrcps_evt_process(hrrcps_evt_t *p_evt)
{
    .....
    case HRRCPS_EVT_SCAN_HRS:
    ....
    error_code = ble_gap_scan_start();
    if (error_code != SDK_SUCCESS)
    {
        hrrcps_op_error_handler(HRRCPS_CTRL_PT_SCAN_HRS);
    }
    g_hrs_active_state = SCAN_DEV_STATE;
    break;
    .....
}
```

### 4.2.3 Command to Enable HRS Notification

HRRCPS parses the command and reports the **HRRCPS\_EVT\_ENABLE\_HRS\_NTF** event to the application layer; HRRCPS then enables HRS notification and relays the received heart rate data to GRToolbox.

### Path: user\_app\user\_app.c under the project directory

#### Name: hrrcps\_evt\_process()

```
static void hrrcps_evt_process(hrrcps_evt_t *p_evt)
{
    ...
    case HRRCPS_EVT_ENABLE_HRS_NTF:
        error_code = hrs_c_heart_rate_meas_notify_set(s_conn_idx_hrs_c, true);
        if (error_code != SDK_SUCCESS)
        {
            hrrcps_op_error_handler(HRRCPS_CTRL_PT_HRS_NTF_ENABLE);
        }
        s_user_write_id = USER_WR_HRS_NTF_EN;
        APP_LOG_DEBUG("Enable HRS notification.");
        break;
    ...
}
```

**Path:** user\_app\user\_app.c under the project directory

```
Name: hrs_c_evt_process ()
```

```
static void hrs_c_evt_process(hrs_c_evt_t *p_evt)
{
    ...
    case HRS_C_EVT_HR_MEAS_VAL_RECEIVE:
        for (rr_intervals_idx = 0; rr_intervals_idx < p_evt-
>value.hr_meas_buff.rr_intervals_num; rr_intervals_idx++)
        {
            hrs_rr_interval_add(p_evt->value.hr_meas_buff.rr_intervals[rr_intervals_idx]);
            hrs_sensor_contact_detected_update(p_evt-
>value.hr_meas_buff.is_sensor_contact_detected);
            hrs_heart_rate_measurement_send(s_conn_idx_collector,p_evt-
>value.hr_meas_buff.hr_value, p_evt->value.hr_meas_buff.energy_expended);
            break;
    ...
}
```

### 4.2.4 Command to Obtain the HRS Device Location

HRRCPS parses the command and reports the **HRRCPS\_EVT\_HRS\_SENSOR\_LOC\_READ** event to the application layer in Bluetooth LE Protocol Stack; HRRCPS then reads the HRS device location and relays the data obtained to GRToolbox.

Path: user\_app\user\_app.c under the project directory

Name: hrrcps\_evt\_process()

```
static void hrrcps_evt_process(hrrcps_evt_t *p_evt)
{
    .....
    case HRRCPS_EVT_HRS_SENSOR_LOC_READ:
        error_code = hrs_c_sensor_loc_read(s_conn_idx_hrs_c);
        if (error_code != SDK_SUCCESS)
        {
            hrrcps_op_error_handler(HRRCPS_CTRL_PT_HRS_SEN_LOC_READ);
        }
}
```

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```
APP_LOG_DEBUG("Read HRS sensor location.");
    break;
......
}
```

Path: user\_app\user\_app.c under the project directory

```
Name: hrs_c_evt_process ()
```

```
static void hrs_c_evt_process(hrs_c_evt_t *p_evt)
{
    ...
    case HRS_C_EVT_SENSOR_LOC_READ_RSP:
        APP_LOG_DEBUG("HRS sensor location is got.");
        hrs_sensor_location_set((hrs_sensor_loc_t)p_evt->value.sensor_loc);
        rsp_val.cmd_id = HRRCPS_CTRL_PT_HRS_SEN_LOC_READ;
        rsp_val.rsp_id = HRRCPS_RSP_ID_OK;
        rsp_val.is_inc_prama = true;
        rsp_val.rsp_param = p_evt->value.sensor_loc;
        error_code = hrrcps_ctrl_pt_rsp_send(s_conn_idx_collector,&rsp_val);
        APP_ERROR_CHECK(error_code);
        break;
        ...
}
```

### **Note**:

You can use GRToolbox to control the interactions between the HRS RSCS Relay device and the RSCS device, which are similar to the procedures mentioned above, and therefore are not explained in this document.